Josh Roy

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EDUCATION

Brown University

Class of 2020

Sc. M. in Computer Science, GPA: 4.0/4.0

- **Selected Courses:** Decision Making under Uncertainty, Language Processing in Humans & Machines, Advanced Algorithms, Computer Vision for Graphics/Interaction
- Thesis: Visual Transfer for Reinforcement Learning via Wasserstein Domain Confusion

Brown University

Class of 2019

Sc. B. in Computer Science with Honors, Major GPA: 3.82/4.0

- **Selected Courses:** Robotics (Grad level), Artificial Intelligence (Grad level), Computer Vision (Grad level), Prescriptive Analytics (Grad level)
- Honors Thesis: Learning Feature Extraction for Transfer from Simulation to Reality
- Activities: Hack@Brown Hardware Team Lead, Brown CS Head Teaching Assistant & Teaching Assistant, Taekwondo Club Instructor & Tournament Organizer

PUBLICATIONS

- Visual Transfer for Reinforcement Learning via Wasserstein Domain Confusion Josh Roy, George Konidaris
 - Proceedings of the AAAI Conference on Artificial Intelligence 2021
- Advanced Autonomy on Low-Cost Educational Platform

 L. Eller*, T. Guérin*, B. Huang*, G. Warren*, S. Yang*, J. Roy, S. Tellex

 RoboCup Best Paper Finalist (3 out of 1,127 accepted papers), Oral Presentation
 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2019
- PiDrone: An Autonomous Educational Drone using Raspberry Pi and Python Isaiah Brand*, Josh Roy*, Aaron Ray, John Oberlin, Stefanie Tellex IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2018
- PiDrone: Design of a Low Cost Autonomous Drone
 Josh Roy*, Isaiah Brand*, John Oberlin, Stefanie Tellex
 CARRE International Research Symposium 2017 (poster session)

PROFESSIONAL EXPERIENCE

BridgerGP

February 2025 - Current

Founding Al Engineer

- First engineer at software startup creating Al agents for financial services
- Creating multi-step decision making systems to communicate with customers, utilize long-term memory, & work with humans in shared digital environments
- Lead collaborative projects to improve AI methodology, performance on internal benchmarks, & create software products to help our end users
- Research/create cutting edge methods: tool calling, multimodality, & multi-step planning

¹ https://scholar.google.com/citations?user=380VVtUAAAAJ&hl=en&oi=ao

Two Sigma Investments

October 2021 - December 2024

Quantitative Software Engineer

- Led projects & collaborated with traders/researchers to create ML models to predict markets, decision-making systems to buy/sell stocks, & production data pipelines as part of Systematic Macro Engineering team
- Independently identified & improved stock-trading planner by fitting & evaluating linear
 & non-linear regressions on historical trading data
- o Built & validated more than 100 new input features in ML models
- Engineered scalable, low-latency distributed systems for machine learning & real-time data processing in trading, implemented at large scale

Cognex

Machine Learning Engineer Machine Learning Intern

June 2020 - October 2021

Summer 2019

- Worked with Al algorithms, 3d vision, & product teams to implement deep learning algorithms & create software for embedded smart cameras to address customer needs
- Researched & productized novel reinforcement learning from human feedback (RLHF), explainable defect-detection (based on YOLOv3), & clustering (based on t-SNE) algorithms for rapid adaptation/deployment to robotic factory automation applications including car assembly, shipping/logistics, & food processing
- Created model distillation & neural network quantization algorithms & implemented low-latency semantic segmentation (UNet) in embedded C++, retaining accuracy

NVIDIA Summer 2018

Deep Learning Intern

- Conducted deep reinforcement learning research for control/motion planning of robots focusing on sim2real with large scale reinforcement learning
- Built mobile robot to guide visitors to meeting rooms combining motion planning, deep learning for computer vision, and neuro-symbolic reasoning

Brown University

Fall 2017 - Spring 2019

Systems Programmer, Operator, Consultant (SPOC)

 Responsible for managing and maintaining distributed system of university computers and related software

RESEARCH & TEACHING EXPERIENCE

Machine Learning Collective

June 2020 - November 2021

Independent Researcher (Part-Time)

 Conducted novel research on two projects: (1) Unsupervised contrastive representation learning from videos via temporal correspondence, (2) Generalization for reinforcement learning via mapping to hierarchical state representation

Brown University VC Inclusion Lab

Fall 2019 - June 2020

Graduate Data Scientist

Led staff to collect, clean, and analyze diverse data and draw business insights.

Created ML pipelines to analyze & visualize data for internal and external stakeholders

Brown University Robotics

Summer 2016 - Summer 2020

Research Assistant

- Advised by Stefanie Tellex, George Konidaris, & James Tompkin at the bigAl initiative
- Research topics included Reinforcement Learning, Classical Planning, Model-Based Reasoning, Planning under Uncertainty, Generative Modeling for Vision/Language, and Representation Learning, among others
- Created Brown CS course: Intro to Robotics. Used by MIT Duckietown, Summer@Brown, other universities and high schools

Brown University Computer Science

Fall 2016 - Spring 2020

Computer Vision (Teaching Assistant)

Spring 2019 & Spring 2020

Deep Learning (TA)

Spring 2018

Logic for Systems (TA)Introduction to Robotics (Head Teaching Assistant)

Fall 2017 & Fall 2018

Graduate Robotics Seminar (HTA)

Spring 2017

Fall 2019

Designing Humanity Centered Robots (HTA)

Fall 2016

AWARDS & MENTIONS

- Two Sigma Internal Al Hackathon Best Project, 2023
- National Science Foundation Graduate Research Fellowship, Honorable Mention, 2020
- RoboCup Best Paper Finalist, IROS, 2019
- Sigma Xi Scientific Research Honor Society, Elected, 2019
- Michael Black Teaching Assistantship Award, Brown University, 2019
- Senior Prize in Computer Science, Brown University, 2019
- Academic Honors in Computer Science, Brown University, 2019
- Welcoming Our New Robot Overlords, New Yorker, October 16 2017

RESEARCH TALKS

• Wasserstein Adversarial Proximal Policy Optimization

Deep Learning Classics and Trends, ML Collective, 2021

• To Infinite (Visual) Transfer and Beyond

Brown University Robotics, 2021

• Making Al See like Humans

Finalist at Research Matters Competition 2020, Brown University Graduate School

How to Make Al See like Humans

Nerd Nite Providence, Brown University Love Data Week, 2020

ACADEMIC SERVICE

Volunteer: AAAI 2021, Neurips 2020

Reviewer: AAAI 2021, Challenges of Real World Reinforcement Learning 2020, ICRA 2020, NeurIPS Reproducibility Challenge 2019, International Symposium on Technology And Society (ISTAS) 2019, IROS 2019, IROS 2018

Technical Blog Posts: https://medium.com/@thosehippos